

# Commonly used DSP formulae

## IIR filter pre-warp

$$\omega_a = \frac{2}{\Delta t} \tan\left(\frac{\omega_d \Delta t}{2}\right) \quad (5.16)$$

## Bilinear transformation

$$s = \frac{2(1 - z^{-1})}{\Delta t(1 + z^{-1})} \quad (5.19)$$

For a BPF replace  $z^{-1}$  in the LPF by:

$$z_{LP}^{-1} = \frac{-z^{-1}(z^{-1} - \alpha)}{(1 - \alpha z^{-1})}$$

where:

$$\alpha = \frac{\cos\left[\frac{\pi(\omega_{cu} + \omega_{cl})}{\omega_s}\right]}{\cos\left[\frac{\pi(\omega_{cu} - \omega_{cl})}{\omega_s}\right]}$$

The LPF cutoff frequency  $\omega_{C_{LP}} = \omega_{cu} - \omega_{cl}$  and the stopband frequency  $\omega_{S_{LP}} = \omega_{C_{LP}} + \Delta\omega$ , where  $\Delta\omega$  is the transition bandwidth. This yields:

$$z = z_{BP} = \frac{1}{2} \left[ \alpha(z_{LP} + 1) \pm \sqrt{\alpha^2 (z_{LP} + 1)^2 - 4 z_{LP}} \right]$$

$$p_{BP} = \frac{1}{2} \left[ -\alpha(p_{LP} + 1) \pm \sqrt{\alpha^2 (p_{LP} + 1)^2 - 4 p_{LP}} \right]$$

For a BSF replace  $z^{-1}$  in the LPF by:  $+z^{-1}(z^{-1} - \alpha) / (1 - \alpha z^{-1})$ . This time the LPF cutoff should be  $\omega_{C_{LP}} = (\omega_s/2) - (\omega_{cu} - \omega_{cl})$ . This yields:

$$z_{BS} = \frac{1}{2} \left[ -\alpha(z_{LP} - 1) \pm \sqrt{\alpha^2 (z_{LP} - 1)^2 + 4 z_{LP}} \right]$$

$$p_{BS} = \frac{1}{2} \left[ -\alpha(p_{LP} - 1) \pm \sqrt{\alpha^2 (p_{LP} - 1)^2 + 4 p_{LP}} \right]$$

## FIR Filter Coefficients

$$c_n = \frac{\Delta t}{\pi} \int_0^{\pi/\Delta t} H_D(\omega) \cos(n\omega\Delta t) d\omega \quad (6.6)$$

**Window Characteristics - Table 6.1**

| Window             | Transition Band (Hz)    | Stopband Rejection (dB) |
|--------------------|-------------------------|-------------------------|
| rectangular        | $\frac{1}{N\Delta t}$   | 21                      |
| Hanning            | $\frac{3.1}{N\Delta t}$ | 44                      |
| Hamming            | $\frac{3.3}{N\Delta t}$ | 53                      |
| Kaiser $\beta = 6$ | $\frac{4}{N\Delta t}$   | 63                      |
| Blackman           | $\frac{5.5}{N\Delta t}$ | 74                      |
| Kaiser $\beta = 9$ | $\frac{5.7}{N\Delta t}$ | 90                      |

**Hanning Window**

$$w_n = \frac{1}{2} \left( 1 + \cos\left(\frac{n\pi}{M}\right) \right) \quad (6.10)$$

**Hamming Window**

$$w_n = 0.54 + 0.46 \cos\left(\frac{n\pi}{M}\right) \quad (6.11)$$

Filter  $h(t)$  matched to signal  $f(t)$

$$h(t) = kf^*(t_m - t) \quad (6.23)$$

or equivalently

$$H(\omega) = kF^*(\omega) \exp(-j\omega t_m)$$

**z-transform of Filter Output Autocorrelation Sequence**

input  $x$  output  $y$

$$S_{yy}(z) = H(z) H(z^{-1}) S_{xx}(z) \quad (7.12)$$

**z-transform of Filter Input/Output Cross-Correlation Sequence**

input  $x$  output  $y$

$$S_{xy}(z) = H(z) S_{xx}(z) \quad (7.15)$$

**The noise variance at the output of a filter  $\sum_{i=0}^N a_i z^{-i} / (1 - \sum_{i=1}^N b_i z^{-1})$  is given by the solution to:**

$$\mathbf{B} [ c_0 \ c_1 \ c_2 \ \cdots \ c_N ]^T = \mathbf{a} \quad (7.19)$$

where

$$\mathbf{B} = \left\{ \begin{bmatrix} 1 & -b_1 & -b_2 & \cdots & -b_N \\ 0 & 1 & -b_1 & \cdots & -b_{N-1} \\ 0 & 0 & 1 & \cdots & -b_{N-2} \\ \cdot & \cdot & \cdot & \cdots & \cdot \\ \cdot & \cdot & \cdot & \cdots & \cdot \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & \cdots & -b_{N-2} & -b_{N-1} & -b_N \\ -b_1 & \cdots & -b_{N-1} & -b_N & 0 \\ -b_2 & \cdots & -b_N & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdots & \cdot & \cdot & \cdot \\ -b_N & \cdots & 0 & 0 & 0 \end{bmatrix} \right\};$$

$$\mathbf{a} = \begin{bmatrix} a_0 & a_1 & a_2 & \cdots & a_N \\ 0 & a_0 & a_1 & \cdots & a_{N-1} \\ 0 & 0 & a_0 & \cdots & a_{N-2} \\ \cdot & \cdot & \cdot & \cdots & \cdot \\ \cdot & \cdot & \cdot & \cdots & \cdot \\ 0 & 0 & 0 & 0 & a_0 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \cdot \\ \cdot \\ a_N \end{bmatrix}$$

The noise variance at the output is:  $\sigma_y^2 = \sigma_x^2 2c_0$

### Wiener Filter

input y output x

$$\Phi_{yy} \mathbf{h}_{opt} = \Phi_{yx} \quad (8.8)$$

### Minimum MSE

$$\eta_{opt} = E[ x^2(n) ] - \mathbf{h}_{opt}^T \Phi_{yx} \quad (8.10)$$

### LMS Adaptive Filter

input y output x

$$e(n) = x(n) - \mathbf{h}^T(n-1) \mathbf{y}(n) \quad (8.29)$$

$$\mathbf{h}(n) = \mathbf{h}(n-1) + 2 \mu \mathbf{y}(n) e(n) \quad (8.30)$$

### LS filter

$$\mathbf{R}_{yy}(n) \mathbf{h}(n) = \mathbf{r}_{yx}(n) \quad (8.13)$$

### RLS Adaptive Filter

input y output x

$$\mathbf{h}(n) = \mathbf{h}(n-1) + \mathbf{R}_{yy}^{-1} \mathbf{y}(n) e(n) \quad (8.18)$$

$$\mathbf{R}_{yy}^{-1}(n) = \mathbf{R}_{yy}^{-1}(n-1) - \frac{\mathbf{R}_{yy}^{-1}(n-1) \mathbf{y}(n) \mathbf{y}^T(n) \mathbf{R}_{yy}^{-1}(n-1)}{\left( 1 + \mathbf{y}^T(n) \mathbf{R}_{yy}^{-1}(n-1) \mathbf{y}(n) \right)} \quad (8.20)$$

**DFT**

$$X(k) = \sum_{n=0}^{N-1} x(n) \exp\left(-j \frac{2\pi nk}{N}\right) \quad (9.12)$$

**Inverse DFT**

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) \exp\left(j \frac{2\pi nk}{N}\right) \quad (9.13)$$

**Power Spectral Density**

$$S_{xx}(\omega) = \sum_{m=-\infty}^{\infty} \phi_{xx}(m) \exp(-j\omega m \Delta t) \quad (9.24)$$

**Autocorrelation**

$$\phi_{xx}(m) = \frac{\Delta t}{2\pi} \int_0^{2\pi/\Delta t} S_{xx}(\omega) \exp(j\omega m \Delta t) d\omega \quad (9.25)$$

**Linear Prediction**

$$\hat{x}(n) = \sum_{i=1}^P a_i x(n-i)$$

**Prediction Error**

$$e(n) = x(n) - \hat{x}(n)$$

**Order- $P$  AR Spectral Estimate**

$$\hat{S}_{xx}(\omega) = \frac{\hat{\sigma}_e^2}{\left| 1 - \sum_{n=1}^P a_n \exp(-jn\omega\Delta t) \right|^2} \quad (9.38)$$